Differential Reduction Algebras

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Basic Idea: From Centralizers to Normalizers

Consider an equation

$$Hf = 0$$

H some linear operator, f in some function space.

If Q is a linear operator commuting with H then Q acts on the solution space:

$$Hf = 0 \Longrightarrow H(Qf) = Q(Hf) = Q(0) = 0$$

Actually, it suffices that $HQ \in AH$ for some algebra A. So let

- \blacktriangleright A be an algebra containing H,
- $I_+ = AH$ be the left ideal generated by H
- ▶ $N = \{Q \in \mathcal{A} \mid I_+Q \subset I_+\}$ be the normalizer of I_+ in \mathcal{A} .

Then N/I_+ is an algebra acting on the solution space

$$\{f \mid Hf = 0\}.$$

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Examples: Laplace, Dirac, Maxwell

$$\Delta f = 0$$

$$\partial f = 0$$

$$\begin{cases} df = 0 \\ d^*f = 0 \end{cases}$$

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Examples: Laplace, Dirac, Maxwell (cont'd)

Each of these operators are images of simple root vectors under an oscillator-type representation $\mathfrak{g} \rightarrow W$:

$$\Delta = \varphi(e_{\alpha}), \qquad \varphi : \mathfrak{sl}_2 \to W(2n)$$

(Zhelobenko?)

$$d = \varphi(e_{\delta_1}), \ d^* = \varphi(e_{\delta_2}), \qquad \varphi : \mathfrak{osp}_{2|2} \to C(2n) \otimes W(2n)$$

(Howe-Lu)

Here W(m), C(m) are Weyl/Clifford algebras on m generators.

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Reduction Algebras

Lie (super)algebra with triangular decomposition

 $\mathfrak{g} = \mathfrak{g}_- \oplus \mathfrak{h} \oplus \mathfrak{g}_+.$

Associative (super)algebra A with a (super)algebra map

 $U(\mathfrak{g}) \to A.$

View A as $U(\mathfrak{g})$ -bimodule. Form the left ideal

$$I_+ = A\mathfrak{g}_+$$

Consider the normalizer

$$N = \{a \in A \mid I_+a \subset I_+\}.$$

The reduction algebra $Z(\mathfrak{g}, A)$ is

$$Z(\mathfrak{g},A)=N/I_+.$$

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Examples

- For each of Laplace, Dirac, Maxwell, the corresponding reduction algebra Z(g, A) acts irreducibly on the solution space.
- ▶ A map $\mathfrak{g} \to \mathfrak{G}$ of Lie (super)algebras gives a reduction algebra

 $Z(\mathfrak{g}, U(\mathfrak{G})).$

This algebra governs the branching rule $\mathfrak{G} \downarrow \mathfrak{g}$.

In particular, the diagonal map g → g × g yields the diagonal reduction algebra

$$\Delta R(\mathfrak{g}) = Z(\mathfrak{g}, U(\mathfrak{g} \times \mathfrak{g})).$$

 $\Delta R(\mathfrak{gl}_n)$ was shown to be braided bialgebra by Khoroshkin and Ogievetsky, being a reflection equation algebra with dynamical R-matrix. $\Delta R(\mathfrak{osp}_{1|2})$ was studied by H* and Williams II (2021,2022).

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"OK, but aren't branching rules known?"

Yes, but reduction algebras

- 1. provide *explicit intertwining operators*, useful in physics eg. Clebsch-Gordan "addition of angular momentum";
- 2. act on multiplicity spaces, not just compute their dimension;
- 3. are "symmetry algebras" for equations of motion in physics;
- 4. are interesting in their own right; precise relationship to dynamical quantum groups not fully understood.

History

The reduction algebras $Z(\mathfrak{g}, \mathfrak{G})$ have been studied extensively when $\mathsf{rk}\,\mathfrak{G} \leq 1 + \mathsf{rk}\,\mathfrak{g}$, including for

- $(\mathfrak{g},\mathfrak{G}) = (\mathfrak{g}(n-1),\mathfrak{g}(n))$ where $\mathfrak{g}(n) = \mathfrak{gl}(n),\mathfrak{sl}(n),\mathfrak{so}(n)$ (van den Hombergh 1976; Zhelobenko 1983–)
- $(\mathfrak{g},\mathfrak{G}) = (\mathfrak{g}(n-1),\mathfrak{g}(n))$ where $\mathfrak{g}(n) = \mathfrak{gl}(m|n), \mathfrak{osp}(n|2m), m$ fixed (Tolstoy 1986)

▶
$$(\mathfrak{g},\mathfrak{G}) = (\mathfrak{so}(n-2),\mathfrak{so}(n))$$
 and $(\mathfrak{sp}(2n-2),\mathfrak{sp}(2n))$ (Molev 2000).

The quantum analog of the reduction algebra, $Z_q(\mathfrak{g}, \mathfrak{G})$, associated to $U_q(\mathfrak{g}) \subset U_q(\mathfrak{G})$ has also been studied for $(\mathfrak{g}, \mathfrak{G}) = (\mathfrak{g}(n-1), \mathfrak{g}(n))$ where $\mathfrak{g}(n) = \mathfrak{su}(n)$ (Tolstoy 1990)

•
$$\mathfrak{g}(n) = \mathfrak{su}(1|n)$$
 (Palev-Tolstoy 1991)

• $\mathfrak{g}(n) = \mathfrak{so}(n)$ and $\mathfrak{sp}(2n)$ (Ashton-Mudrov 2015)

Functoriality?

Given a commutative square



what is the relationship between

$$Z(\mathfrak{g}, A)$$
 and $Z(\mathfrak{G}, B)$?

Some obvious partial answers; in general hard to say.

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Stabilization and Cutting

Khoroshkin-Ogievetsky developed techniques of *stabilization* and *cutting* for commutation relations related to the square

$$\mathfrak{gl}_n \longrightarrow U(\mathfrak{gl}_n) \otimes U(\mathfrak{gl}_n) \longrightarrow \Delta R(\mathfrak{gl}_n)$$

 $\downarrow \qquad \qquad \downarrow$
 $\mathfrak{gl}_{n+m} \longrightarrow U(\mathfrak{gl}_{n+m}) \otimes U(\mathfrak{gl}_{n+m}) \longrightarrow \Delta R(\mathfrak{gl}_{n+m})$

key to their inductive computation of a complete presentation of the diagonal reduction algebra $\Delta R(\mathfrak{gl}_n)$.

• Open Problem: Find a presentation for $\Delta R(\mathfrak{g})$ for $\mathfrak{g} = \mathfrak{so}_n, \mathfrak{sp}_{2n}$. Hard. Try easier cases first: Differential reduction algebras.

Differential Reduction Algebras

Oscillator representations provide homomorphisms

 $\mathfrak{g} \to W$

W is some Weyl/Clifford (super)algebra. Combine with diagonal map:

$$\mathfrak{g}
ightarrow U(\mathfrak{g}) \otimes U(\mathfrak{g})
ightarrow W \otimes U(\mathfrak{g})$$

The corresponding differential reduction algebra is

$$D(\mathfrak{g}) = Z(\mathfrak{g}, W \otimes U(\mathfrak{g})).$$

It controls structure of $\operatorname{\mathfrak{g}-modules}$ of the form

 $\mathbb{C}[\underline{x}] \otimes V.$

Squares of Interest

$$\mathfrak{gl}_n \longrightarrow W \otimes U(\mathfrak{gl}_n) \qquad \rightsquigarrow D(\mathfrak{gl}_n)$$

$$\downarrow \qquad \qquad \downarrow$$

$$\mathfrak{sp}_{2n} \longrightarrow W' \otimes U(\mathfrak{sp}_{2n}) \qquad \rightsquigarrow D(\mathfrak{sp}_{2n})$$

$$\downarrow \qquad \qquad \qquad \downarrow$$

$$\mathfrak{osp}_{1|2n} \longrightarrow W'' \otimes U(\mathfrak{osp}_{1|2n}) \qquad \rightsquigarrow D(\mathfrak{osp}_{1|2n})$$

• The algebra $D(\mathfrak{gl}_n)$ was studied in Herlemont's PhD thesis (2018).

- ▶ In our 2024 paper we give presentation of $D(\mathfrak{sp}_{2n})$ for n = 2.
- The case n > 2 still open, as is $D(\mathfrak{osp}_{1|2n})$.

Presentation of $D(\mathfrak{sp}_4)$

Let $\mathfrak{sp}_4 \to W(4)$ be the natural map and

$$D(\mathfrak{sp}_4) = R \otimes_{U(\mathfrak{h})} Z(\mathfrak{sp}_4, W(4) \otimes U(\mathfrak{sp}_4))$$

where R is the ring of "dynamical scalars"

$$R = \mathbb{C}[H_{lpha}, H_{eta}][(H_{\gamma} - n)^{-1} \mid \gamma \in Q^{\vee}, n \in \mathbb{Z}]$$

Theorem (H*, Williams II (2024))

 $D(\mathfrak{sp}_4)$ is generated as an R-ring by $\bar{x}_1, \bar{\partial}_1, \bar{x}_2, \bar{\partial}_2$ subject to:

$$\begin{split} \bar{x}_i H_j &= (H_j - a_{ij}) \bar{x}_i, \ a_{ij} \in \mathbb{Z} & + dual \ rel. \\ \bar{x}_1 \bar{x}_2 &= \left(1 + \frac{1}{a}\right) \bar{x}_2 \bar{x}_1 & + dual \ rel. \\ \bar{x}_1 \bar{\partial}_2 &= \left(1 + \frac{1}{c}\right) \bar{\partial}_2 \bar{x}_1 & + dual \ rel. \\ \bar{x}_1 \bar{\partial}_1 &= -1 + \frac{1}{a} + f_{11} \bar{\partial}_1 \bar{x}_1 + f_{12} \bar{\partial}_2 \bar{x}_2 & + \bar{x}_2 \bar{\partial}_2 \ rel. \end{split}$$

where

and a

$$f_{11} = rac{(a+1)(a-1)(b+1)}{a^2b}$$
 $f_{12} = rac{-(d+2)}{ac},$
 $= H_lpha + 1, \ b = H_{eta+2lpha} + 1, \ c = H_{eta+lpha} + 1, \ d = H_eta + 1.$

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Limit as " $H_{\gamma} \rightarrow \infty$ "

$$ar{x}_1ar{\partial}_1 = -1 + rac{1}{a} + f_{11}ar{\partial}_1ar{x}_1 + f_{12}ar{\partial}_2ar{x}_2,$$
 $f_{11} = rac{(a+1)(a-1)(b+1)}{a^2b} \qquad f_{12} = rac{-(d+2)}{ac},$

Put

$$D^*(\mathfrak{sp}_4) = \mathbb{C}[\hbar, \hbar^{-1}] \otimes_{\mathbb{C}} D(\mathfrak{sp}_4)$$

Consider the integral form

$$D^0(\mathfrak{sp}_4) = \mathbb{C}[\hbar] \langle H'_{\gamma} = \hbar H_{\gamma}, \ ar{x}_i, \ ar{\partial}_j
angle \subset D^*(\mathfrak{sp}_4)$$

Substituting $H_{\gamma} = \frac{1}{\hbar}H'_{\gamma}$ in above relations we see

$$D^0(\mathfrak{sp}_4)/(\hbar)\cong W(4)\otimes_{\mathbb{C}} U(\mathfrak{h}).$$

Generalized Weyl Algebra Realization

Generalized Weyl algebras were introduced by Bavula.

Theorem (H*, Williams II (2024)) The "normalized" generators of $D(\mathfrak{sp}_4)$:

$$egin{aligned} \widehat{x}_1 &= ar{x}_1, & \widehat{x}_2 &= (H_lpha+2)ar{x}_2, \ \widehat{\partial}_1 &= ar{\partial}_1(H_lpha+1)(H_{eta+lpha}+1), & \widehat{\partial}_2 &= ar{\partial}_2(H_{eta+lpha}+1) \end{aligned}$$

satisfy

$$\begin{split} [\widehat{x}_1, \widehat{x}_2] &= [\widehat{\partial}_1, \widehat{\partial}_2] = [\widehat{x}_1, \widehat{\partial}_2] = [\widehat{x}_2, \widehat{\partial}_1] = 0, \\ \widehat{x}_1 \widehat{\partial}_1 &= C_1 + g_{11} \widehat{\partial}_1 \widehat{x}_1 + g_{12} \widehat{\partial}_2 \widehat{x}_2 \\ \widehat{x}_2 \widehat{\partial}_2 &= C_2 + g_{21} \widehat{\partial}_1 \widehat{x}_1 + g_{22} \widehat{\partial}_2 \widehat{x}_2 \end{split}$$

for certain $C_i, g_{ij} \in R$, making $D(\mathfrak{sp}_4)$ a non-trivial example of a generalized Weyl algebra.

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Tools: Extremal Projector

(Asherova, Smirnov, Tolstoy, ... 1971–) Every reductive Lie algebra
 g = g_− ⊕ h ⊕ g₊ has a unique extremal projector

 $P = P(\mathfrak{g}) \in TU(\mathfrak{g})$ (certain completion of $U(\mathfrak{g})$)

defined by

$$e_{lpha}P = 0 = Pf_{lpha} \ orall lpha \in \Phi_+$$

 $P \cong 1 \ (ext{mod} \ \mathfrak{g}_- TU(\mathfrak{g}) + TU(\mathfrak{g})\mathfrak{g}_+)$

Moreover,

$$P^{2} = P, \qquad [\mathfrak{h}, P] = 0.$$

$$P(\mathfrak{sl}_{2}) = \sum_{n \ge 0} \frac{(-1)^{n}}{n!} \frac{1}{(h+2)\cdots(h+n+1)} f^{n} e^{n}$$

$$P(\mathfrak{sp}_{4}) = P_{\alpha} P_{\beta+2\alpha} P_{\beta+\alpha} P_{\beta} = P_{\beta} P_{\beta+\alpha} P_{\beta+2\alpha} P_{\alpha}$$

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Tools: Double Coset Algebra

▶ (~ Mickelsson 1973,...) Given $\mathfrak{g} \to A$, the map

$$Z(\mathfrak{g},A) = N/I_+ \to I_- \backslash A/I_+$$

is injective, where $I_+ = A\mathfrak{g}_+$, $I_- = \mathfrak{g}_-A$; and bijective after localization at coroots-minus-integers.

 (Zhelobenko; Khoroshkin-Ogievetsky) The product in I₋\A/I₊ making the map an isomorphism is given by

$$\bar{a} \diamond \bar{b} = \overline{aPb}, \qquad \bar{a} = I_- + a + I_+ \in I_- \backslash A/I_+$$

called the diamond product.

Future Directions

- ▶ Find presentation, center, irreps, etc for D(g), g = so_n, sp_{2n}, osp_{1|2n}, maybe using a version of Stabilization and Cutting.
- Do the same for $\Delta R(\mathfrak{g})$.
- ► $Z(\mathfrak{osp}(2|2), C(2n) \otimes W(2n))$ and Maxwell's equations?
- Coupled Dirac+Maxwell?

References

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1. arXiv:2403.15968 [math.RT] Symplectic differential reduction algebras and skew-affine generalized Weyl algebras

Thank you for your attention.